**CLINICAL CONNECTIONS & SETTINGS GUIDE**

K0 allows pattern recognition command of Ottobock DynamicArm Standard elbow flexion/extension with optional pronation/supination of a powered wrist and open/close operation of prosthetic hands. Pattern recognition command of multifunction grips is not included.

### PART 1: PHYSICAL CONNECTIONS

**OTTOBOCK DYNAMICARM STANDARD**
Ensure all settings in the Ottobock Data Station 'Customizing' screen are set exactly as shown.

**OTTOBOCK ELECTRIC WRIST ROTATOR (NO MYOROTRONIC)**
No settings required

**MOTION CONTROL**

**PROHAND, PROETD/ETD2**
**HAND SET UP**
- Input Type: EMG
- Hand Filtering: Quick
- Channel: Dual
- Control: Differential
- Hand Direction: A

**Thresholds/Outputs**
- A: 15
- B: 15

**Input Gains**
- A: 5
- B: 5

### PART 2: SOFTWARE SETTINGS

**WRISTS**

**OTTOBOCK ELECTRIC WRIST ROTATOR (NO MYOROTRONIC)**
No settings required

**HANDS (CONT.)**

**OTTOBOCK SENSORHAND, MYOHAND VARIPLUS, SYSTEM ELECTRIC GREIFER, OR SYSTEM ELECTRIC HAND**
Ensure ‘control mode’/’program’ 1

**PSYONIC ABILITY HAND**
Ensure the "Control System" setting in the PSYONIC ABILITY HAND app is set to "Direct Control"
Ensure all other hand settings in the PSYONIC ABILITY HAND app are set to the factory defaults

**MOTION CONTROL**

**PROHAND, PROETD/ETD2**
**HAND SET UP**
- Input Type: EMG
- Hand Filtering: Quick
- Channel: Dual
- Control: Differential
- Hand Direction: A

**Thresholds/Outputs**
- A: 15
- B: 15

**Input Gains**
- A: 5
- B: 5

**NOTES:**
Many hands will require the 13E100 AnalogAdapter from Ottobock. Consult with Ottobock if your selected hand will require this additional component.

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