K0 allows pattern recognition command of Ottobock DynamicArm Standard elbow flexion/extension with optional pronation/supination of a powered wrist and open/close operation of prosthetic hands. Pattern recognition command of multifunction grips is not included.

PART 1: PHYSICAL CONNECTIONS

**ELBOW**

**OTTBOCK DYNAMICARM STANDARD**
Ensure all settings in the Ottobock Data Station ‘Customizing’ screen are set exactly as shown.

**WRISTS**

**OTTBOCK ELECTRIC WRIST ROTATOR (NO MYOROTRONIC)**
No settings required

**HANDS**

**OTTBOCK SENSORHAND, MYOHAND VARIPLUS, SYSTEM ELECTRIC GREIFER, OR SYSTEM ELECTRIC HAND**
Ensure ‘control mode’/’program’ 1

NOTE: Many hands will require the 13E100 AnalogAdapter from Ottobock. Consult with Ottobock if your selected hand will require this additional component.

PART 2: SOFTWARE SETTINGS

**MOTION CONTROL**

**PROHAND, PROETD/ETD2**
HAND SET UP
- Input Type: EMG
- Hand Filtering: Quick
- Channel: Dual
- Conatrol: Differential
- Hand Direction: A
Thresholds/Outputs
- A: 15
- B: 15
Input Gains
- A: 5
- B: 5

**OTTOBOCK BEBIONIC**
Control Strategy: Dual Site
Open / Close Strategy: Electrodes: A,B
Control Options: Electrodes
Control Response: Proportional
In ELECTRODE SCREEN:
- Channel 1 “Blue” threshold: 10%
- Channel 1 “Red” threshold: 90%
- Channel 2 “Blue” threshold: 10%
- Channel 2 “Red” threshold: 90%
Remember to press “Send to Hand” after making any changes