PART 1: PHYSICAL CONNECTIONS

I0 controls pronation/supination of powered wrists and open/close operation of prosthetic hands. Pattern recognition command of multifunction grips is not included.

**NOTE:** When using an i-Limb Quantum terminal device, connections for Open and Close may need to be reversed to ensure proper operation.

**NOTE:** When using an i-Limb Quantum terminal device, connections for Open and Close may need to be reversed to ensure proper operation.

***MANY/MOST HANDS SHOULD BE SET TO FACTORY DEFAULT FOR OPTIMAL OPERATION.***

**PART 2: SOFTWARE SETTINGS**

**WRISTS**

**OTTOBOCK ELECTRIC WRIST ROTATOR (NO MYOROTRONIC)**
No settings required

**MOTION CONTROL STANDARD WRIST ROTATOR (NO PROCONTROL)**
No settings required

**HANDS**

***MANY/MOST HANDS SHOULD BE SET TO FACTORY DEFAULT FOR OPTIMAL OPERATION.***

**OTTOBOCK SENSORHAND, MYOHAND VARIPLUS, SYSTEM ELECTRIC GREIFER, OR SYSTEM ELECTRIC HAND**
Ensure ‘control mode’/’program’ 1

**OTTOBOCK BEBIONIC**
Control Strategy: Dual Site
Open / Close Strategy: Electrodes: A,B
Control Options: Electrodes
Control Response: Proportional
In ELECTRODE SCREEN:
- Channel 1 “Blue” threshold: 10%, Channel 1 “Red” threshold: 90%, Channel 2 “Blue” threshold: 10%, Channel 2 “Red” threshold: 90%
Remember to press ”Send to Hand” after making any changes

**MOTION CONTROL PROHAND, PROETD/ETD2**
HAND SET UP
- Input Type: EMG, Hand Filtering: Quick, Channel: Dual, Conatrol: Differential, Hand Direction: A
Thresholds/Outputs
- A: 15, B: 15
Input Gains
- A: 5, B: 5