K1 allows pattern recognition command of Ottobock DynamicArm Plus elbow flexion/extension with optional pronation/supination of a powered wrist and open/close operation of prosthetic hands. Pattern recognition command of multifunction grips is not included.

**PART 1: PHYSICAL CONNECTIONS**

**ELBOW**

**OTTOBOCK DYNAMICARM PLUS**
Ensure all settings in the Ottobock ElbowSoft TMR ‘Customizing’ screen are set exactly as shown by clicking the ‘Default’ button.

**WRISTS**

**OTTOBOCK ELECTRIC WRIST ROTATOR (NO MYOROTRONIC)**
No settings required.

**HANDS**

**I-LIMB, TASKA, VINCENTEVOLUTION3, PSYONIC ABILITY HAND, COVVI HAND**
Ensure hand settings are the factory defaults.

**PART 2: SOFTWARE SETTINGS**

**HANDS (CONT.)**

**OTTOBOCK SENSORHAND, MYOHAND VARIPLUS, SYSTEM ELECTRIC GREIFER, OR SYSTEM ELECTRIC HAND**
Ensure ‘control mode’/’program’ 1

**MOTION CONTROL PROHAND, PROETD/ETD2**

**HAND SET UP**
- Input Type: EMG
- Hand Filtering: Quick
- Channel: Dual
- Control: Differential
- Hand Direction: A

**Thresholds/Outputs**
- A: 15
- B: 15

**Input Gains**
- A: 5
- B: 5